| TPM CIRCLE NO :- 3 | | | - 3 | | ACTIVITY | KK | QM | PM | JH | SHE | ОТ | DM | E&T | 1/ 1 17 | | | | |
|--|---------------------------------|-----------------|--|----------------------------|---------------|---|-------|------|----|------|---------------------------------------|----------------------------|-----------|----------------|--------------|---------|---------------|--|
| ADVIK P1 | TPM CIRCLE NAME : | | | LOSS NO. / STEP | | | | | | | | | | ≒ KAIZEN IDEAS | | | HEEL | |
| | DEPT :- Q.A | | | RESULT AREA P Q DEF :- A C | | | | | | С | D | S | М | | | | | |
| CELL:- A361 L CELI | ELL :- A361 L CELL NAME:- Lever | | | | | MACHINE / STAGE :- VMC OPERATION :- Drilling. | | | | | | | | | | | | |
| KAIZEN THEME – To avoid Neutral position NG (At assembly stage | | | IDEA :- Hydraulic clamping to be provided to avoid dia 2.3 hole shift. COUNTERMEACURE(1) Under this plantage to be BENCHMARK 473No. | | | | | | | | | | | | | | | |
| neutral position NG). | | | countermeasure:1) Hydraulic clamping to be provided 2) Training given to operator | | | | | | | | TARGET | | | | 0 No. | | | |
| WIDELY/DEEPLY:- | | | | | | | | | | | | | | | 7.2014 | | | |
| | | | | 1 | | | | | | | | | T DAT | | | 6.2015 | | |
| PROBLEM / PRESENT | STATUS - | - Neutro | al | | | | | | | | | | N FINIS | | | | | |
| position NG (At assembly stage | | | | | | | | | | | TEAM MEMBERS :- | | | | | | | |
| neutral position NG). | | | | | | | | | | U | Umesh Pimple, Ajit Deokar | | | | | | | |
| The state of the s | | | | | | | | | | | Ganesh Padwalkar ,Vijay Walunj | | | | | | | |
| | | | | | | | | | | L | BENEF | ITS :- | | | | | | |
| | | | | | | | | | | 1 | l. Pr | event | Re-occ | urrenc | e Defe | ct. | | |
| | | | | | | | | | | | 2. Reduce COPQ. | | | | | | | |
| | N. of | | | | | | | | | | ' | 2. KE | euuce | COPQ. | | | | |
| | | | | | | | | | | | | | | | | | | |
| | C. | | | | | | | | | | - | | | | | | | |
| 4 | | | | | | | | | | | | | KA | IZEN SU | ISTEN | NCE | | |
| | 10.00 | _ | | 1 | | | | | _ | | | | | | | | | |
| Manual Clamping | | | BEFORE | | | | | | | AFTE | N | | _ | O- Poi | | | | |
| AATIN AATIN AATAINGIC | | | | DECL | IT. | | | | ! | | − F | ixtur | re ma | intenar | ice che | ck she | et . | |
| WHY - WHY ANALYSIS:- | | | RESU | RESULT :- | | | | | | | | HOW TO DO: Audit | | | | | | |
| Why 1 – Neutral position NG (After assembly stage neutral position NG). | | | | | | | | | | | FREQ | UENC | CY : Alte | ernate | Day | | | |
| stage neutral position | ING). | | | | | | | | | | | | | | | - | | |
| | | | | | | | | | | | | | | | | | | |
| Why 2 - During drilling | nart aet | t vibrate | 1 | | | | | | | 7 | | | | | | | | |
| Willy 2 Donning armining | pan goi | 1 VIDIGIO | • | | urrently 100 | % | | | | | | | | | | | | |
| Why 3 -Clamping in a | complete | e . | | | • | | .1~+: | 0.10 | | | _ | | | | | | | |
| , | | | | | rspection wit | n re | elati | on | | | C | OST I | INCU | RRED FO | OR MA | KING H | CAIZEN | |
| Why 4 -Current process allows in complete | | | gauge | | | | | | | N | MATERIAL COST LABOUR COST TOTAL COS | | | | | L COST | | |
| clamping .(Manual clamping) | | | D~~D~ | | | | | | | L | IN RS IN RS IN RS | | | | | RS | | |
| ROOT CAUSE Curren | t process | s allows i | in | | | | | | | | | | | | | | | |
| complete clamping. | • | J G.1.0 113 1 | | | | | | | | | 50 | ODE 0 | DIAN | EOD HO | DIZONIT | AL DEDI | OVNAENI | |
| · · · · · · · · · · · · · · · · · · · | | | | | | | | | | | SCOPE & PLAN FOR HORIZONTAL DEPLOYMEN | | | | | | | |
| REGISTRATION NO. & DATE:- 15.07.2014 | | | | | | | | | | | | NO. CELL TARGET RESPONSIBI | | | SIBILITY | STATUS | | |
| REGISTERED BY :- Ganesh Padwalkar | | | | | | | | | | | | A29 | 94 | 25 05 15 | Mr.A | ijeet | In- | |
| MANAGER'S SIGN :- Sunil kinkar | | | | | | | | | | | - | | tor | 25.05.15 | Dec | - | Process | |